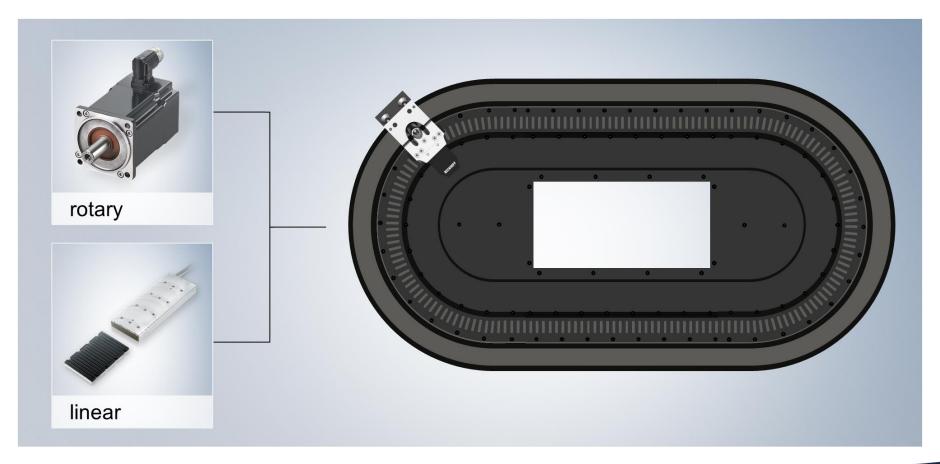


### Linear Transport Systems



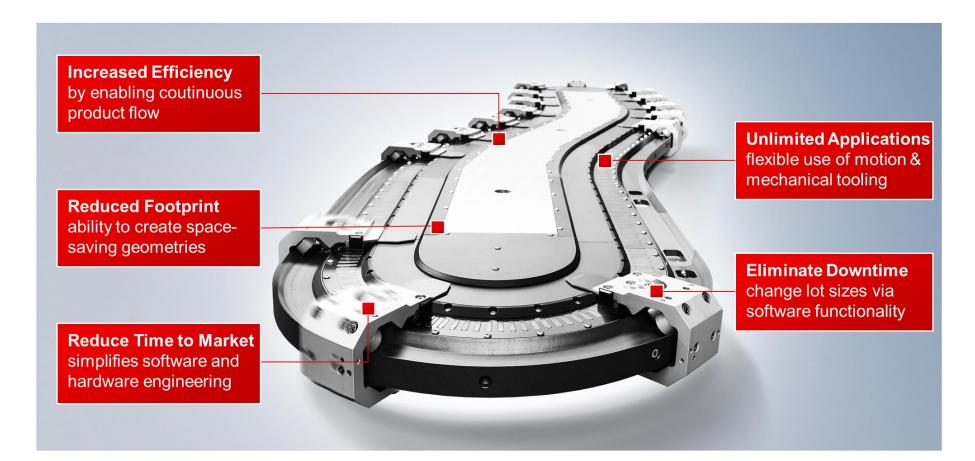


# Linear Transport Systems – combine rotary and linear technology





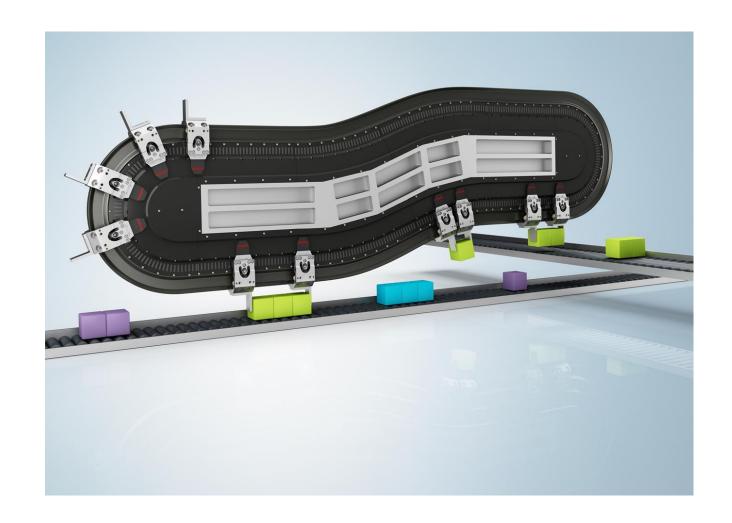
### Linear Transport Systems – benefits





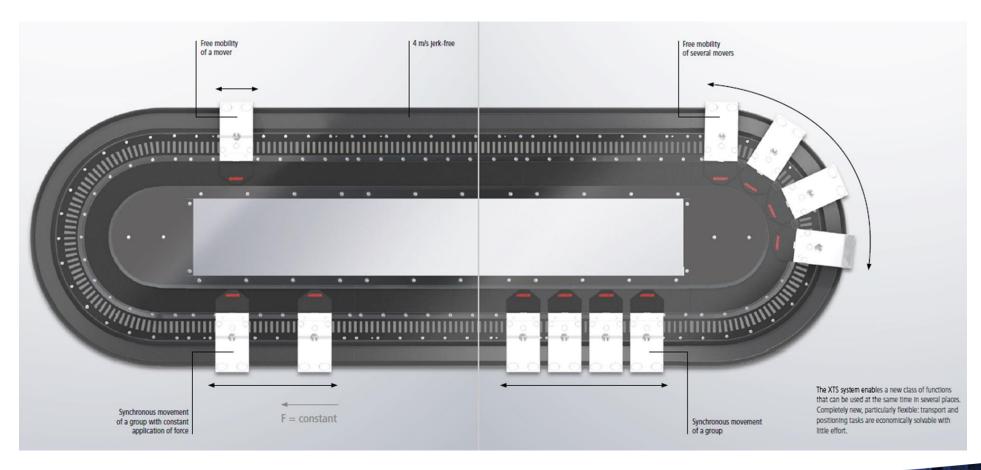
## A revolutionary distribution system

- Outstanding dynamics allows selective processing without interrupting coutinuous product flow.
- Individual movers can work independently on multiple products.
- Products can be transported individually or in groups.
- Synchronization with selective stopping and starting at any position.
- Maximum positioning accuracy and jerkfree accelerations.





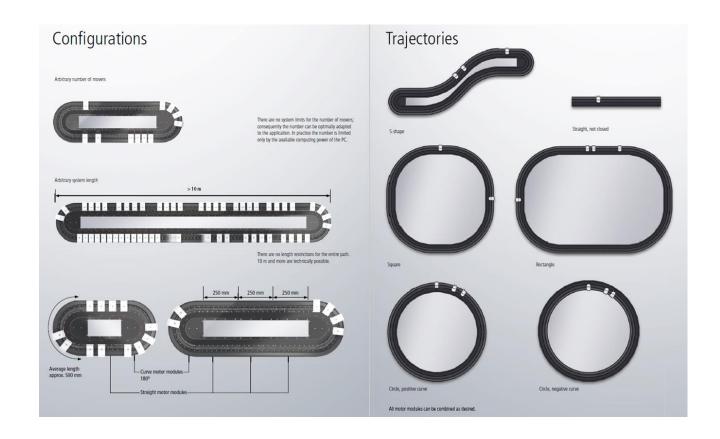
### Linear Transport Systems – basic functions





## Functioning as a distribution system

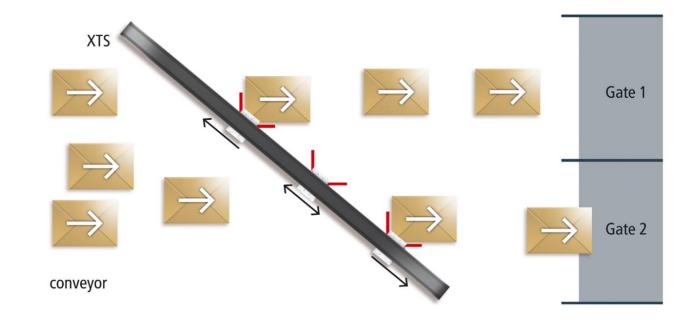
- Freely-selectable track layouts and number of movers.
- Individual and group controllability.
- Ease of integration into existing environments.
- Implementation of motion and handling tasks to allow new and innovative mechanical designs.





## A distribution system for product sortation

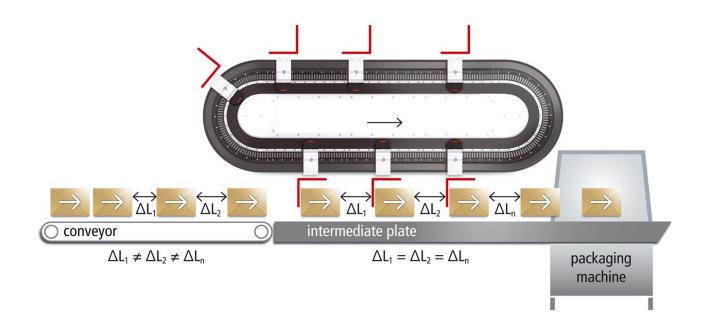
- Functions as a distribution system.
- XTS splits incoming product stream into multiple lanes.
- Flexibility, with lanes easily added or removed.





# Gapping asynchronious product flow

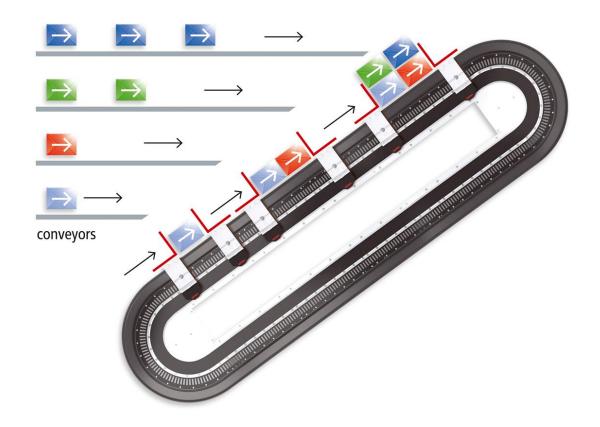
- XTS makes it easy to implement gap control.
- Uses distance adjustments that synchronize product arrviving at different intervals.
- Creates consistent gap of product to downstream process.





#### Grouping products

- Multiple movers can work together to clamp or hold products.
- XTS can combine multiple products arriving on multiple conveyors into predefined and easily changeable groups and move them to the next station.
- Operations can adapt to product width, stack height and number of stacks without manual changeover.
- Distance between movers and motion profile can be changed on the fly without stopping.

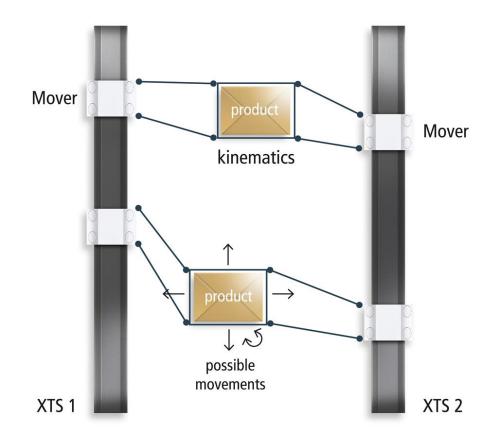






### Rotating product with kinematics

- With circulating kinematics, the transported product can be influenced in X and Y directions.
- With two XTS sytems arranged in parallel, the manipulator is synchronized to the product and shifts it on the belt at full speed.
- Product can even be rotated slightly using appropriate kinematics.





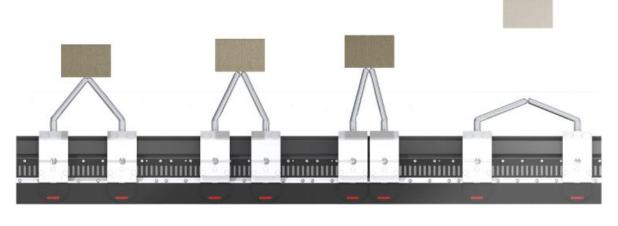
#### Unlimited application possibilities

Push product or change spacing. Reduce or increase product speed.

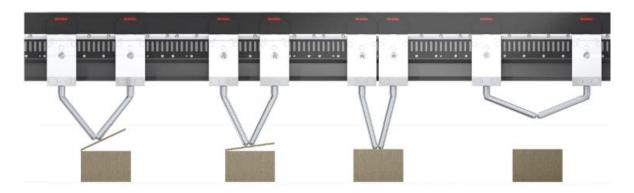


Clamp and move product.

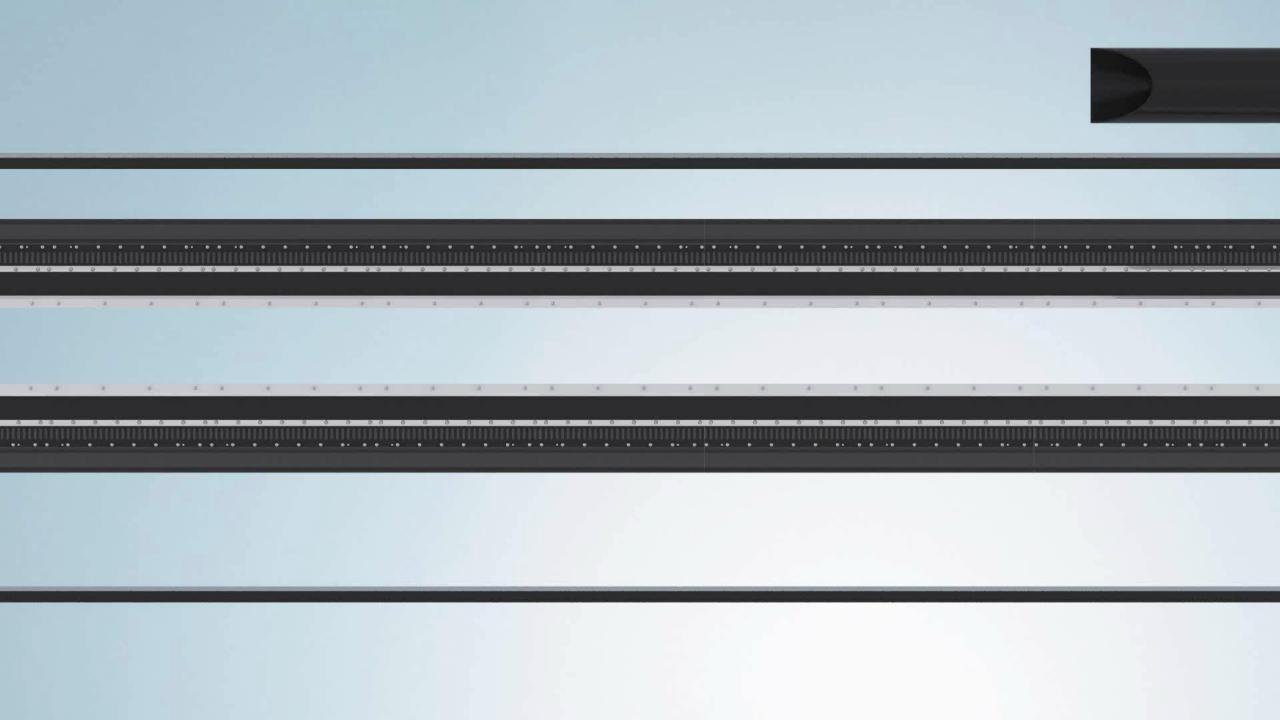




Apply kinematics in linear motion for lifting or pressing.

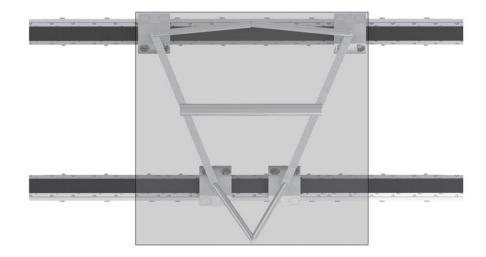


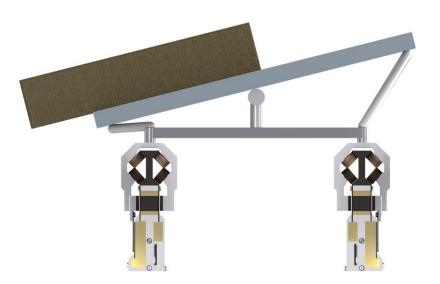




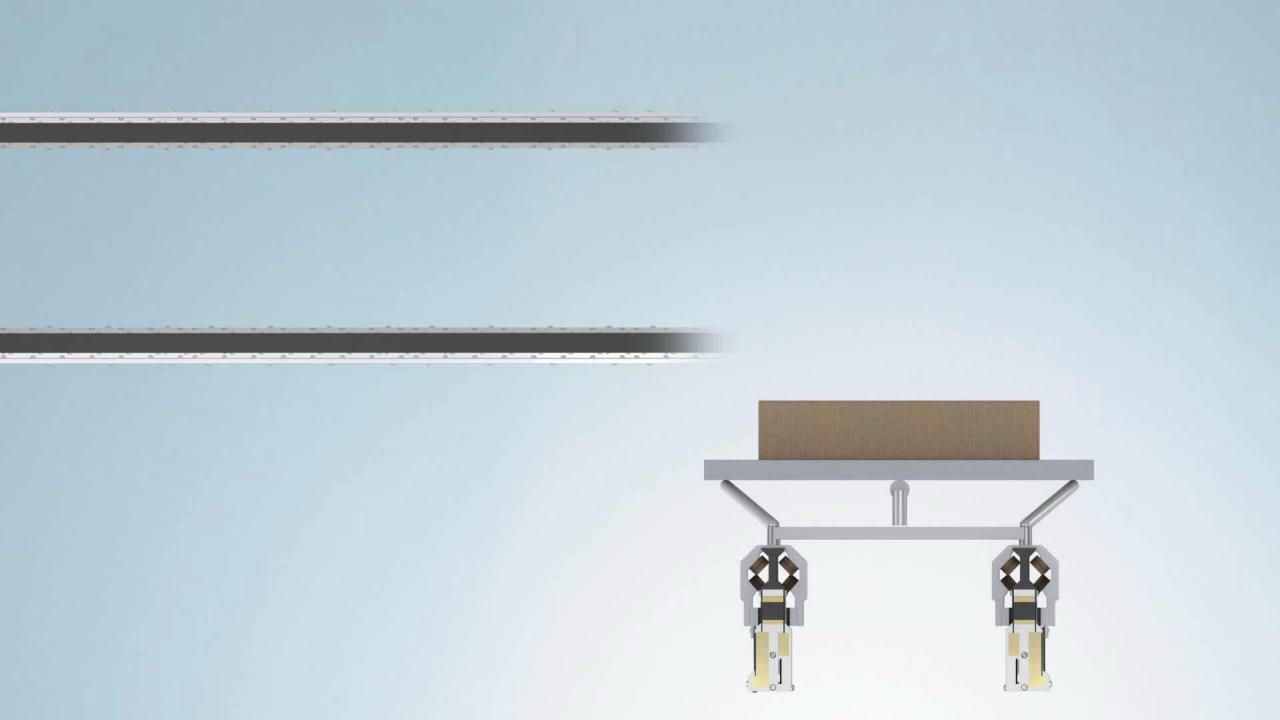
## Unlimited application possibilities

 With multiple movers and innovative tooling, XTS can also transport and discharge product.



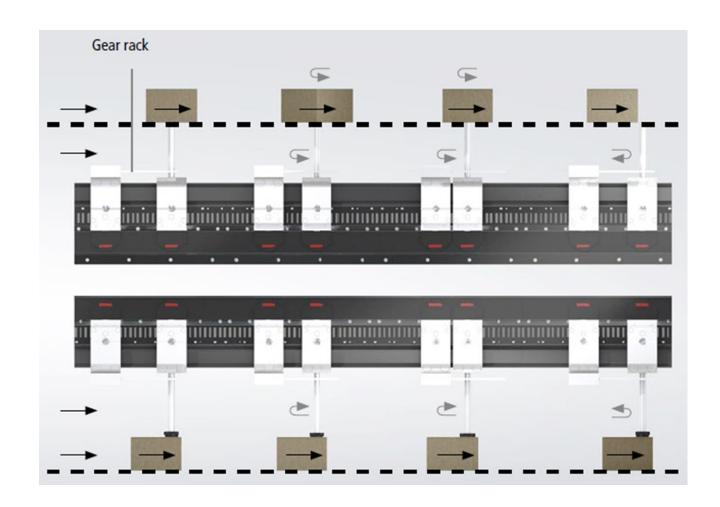






## Unlimited application possibilities

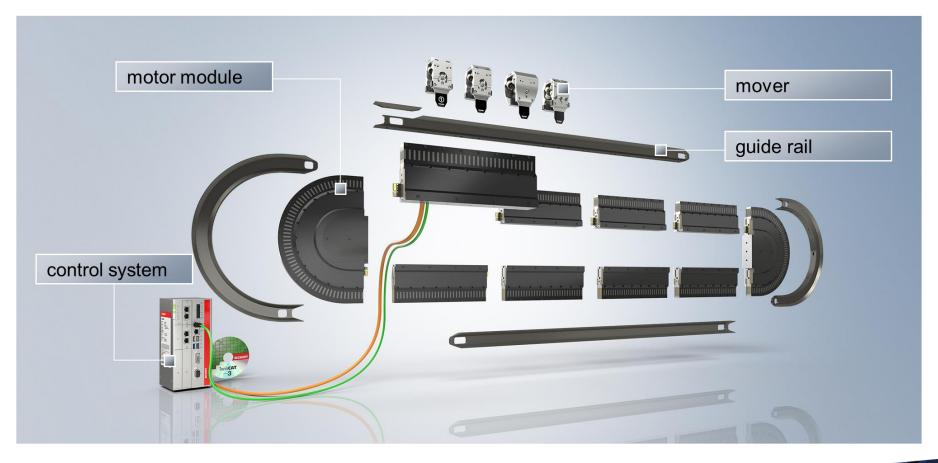
 Kinematics in linear motion for turning product or closing a cap.





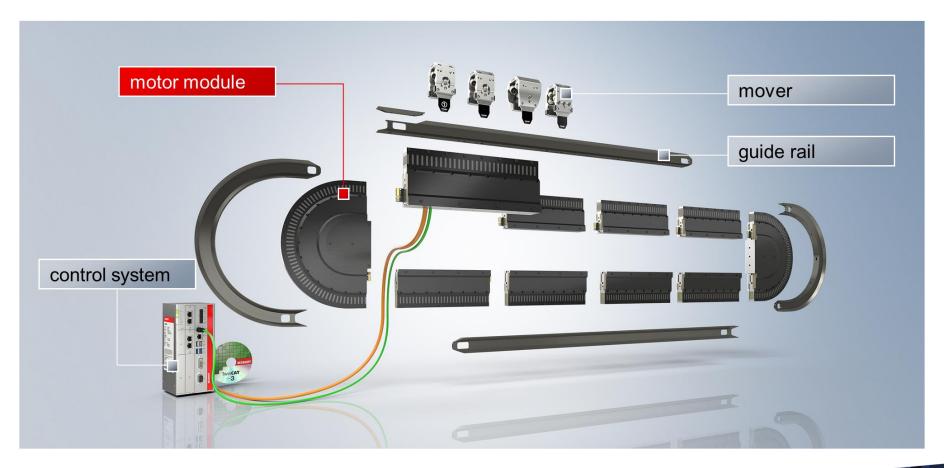


# The modular XTS system: reduces time to market





## The modular XTS system: motor modules





# XTS motor modules: everything incorporated in a single mechatronic component

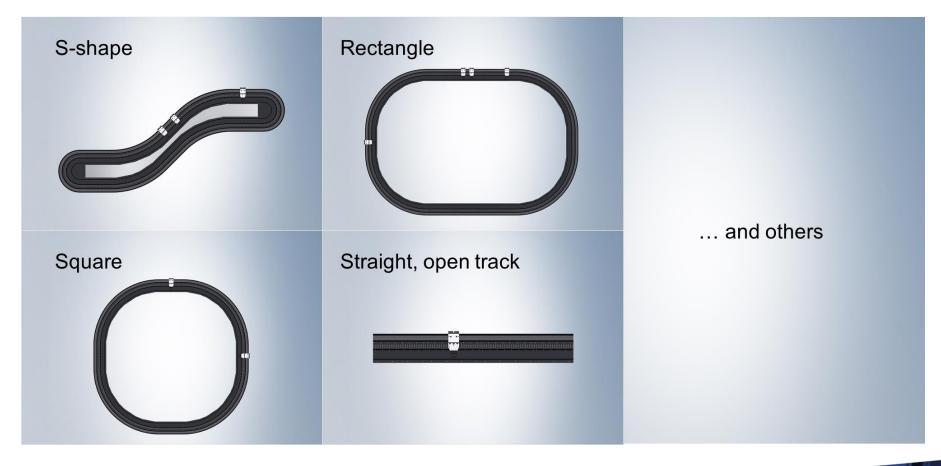
System properties		
Max. force	100 N 80 N	at standstill at 2 m/s
Continuous force	30 N	(at < 30 °C temperature increase in the motor compared to mounting frame)
Speed	4 m/s	at 48 V DC supply
Acceleration	> 100 m/s <sup>2</sup>	(without payload)
Positioning accuracy	< ±0.15 mm	at 1.5 m/s possible within a straight module
Absolute accuracy	< ±0.25 mm	possible within a straight module
Repeatability	< ± 10 µm	(stillstand unidirectional)
Max. system length	> 100 m	(dependent on computing power, no system limit)
Power consumption per motor module at 24 V DC	30 W/m	for communication, electronics, position feedback
Length per infeed	max. 3 m	voltage supply, EtherCAT
Protection rating	motor modules:	IP 65
Approvals	CE, UL	



# XTS motor modules: everything incorporated in a single mechatronic component

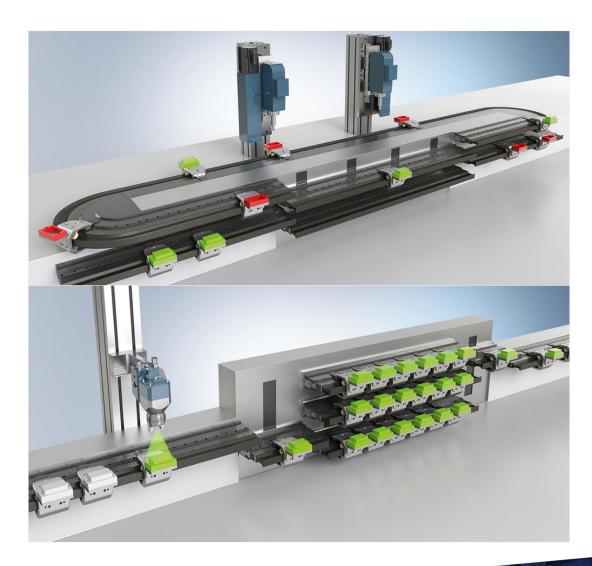


# XTS motor modules: flexible track layouts



#### XTS Track Management: new flexibility in motion control

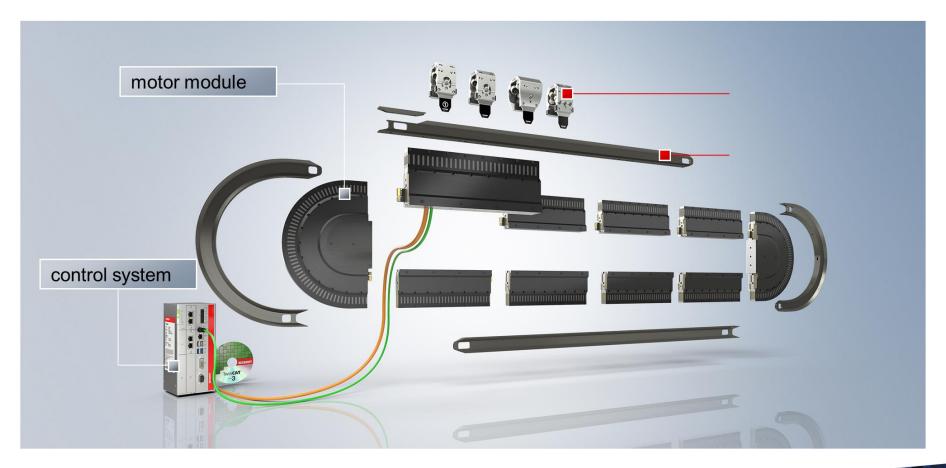
- Track sections can be moved.
- Exchange movers between tracks.
- Motor modules and movers remain fully operational at all times.
- Maximum flexibility without downtime.
- Small footprint combined with maximum parts buffer capacity.



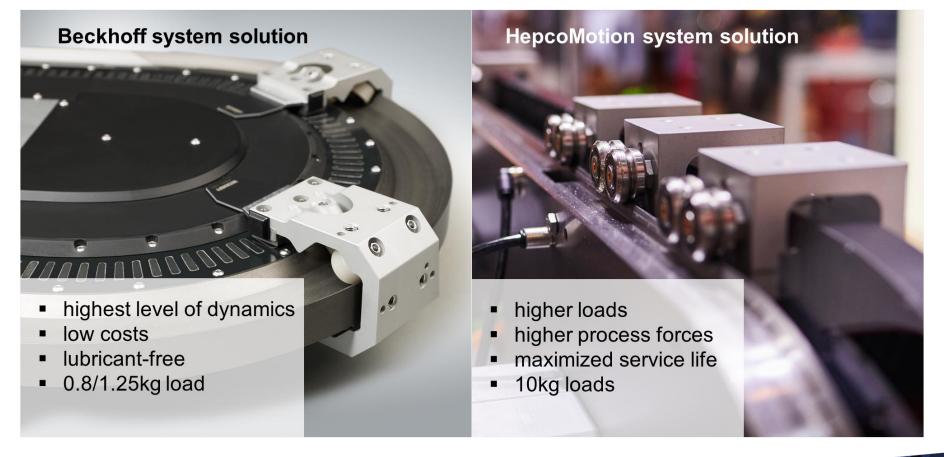




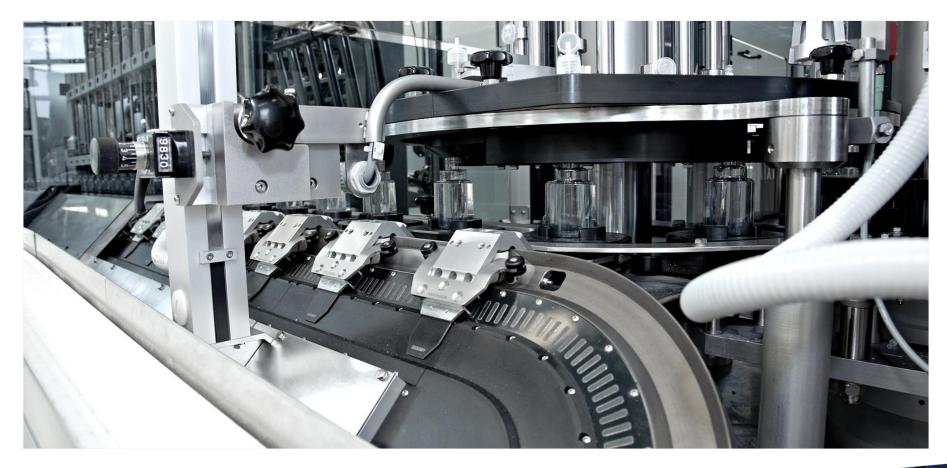
# The modular XTS system: guide rails and movers



# The modular XTS system: guide rails and movers – comparison



# Application example: cosmetics filling line – groninger & Co. GmbH, Germany



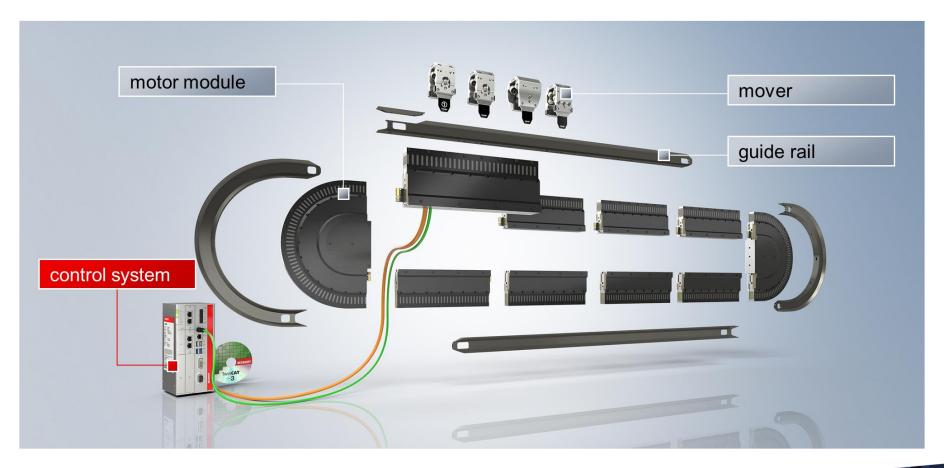


## Application example: optical inspection system – GEFASOFT, Germany





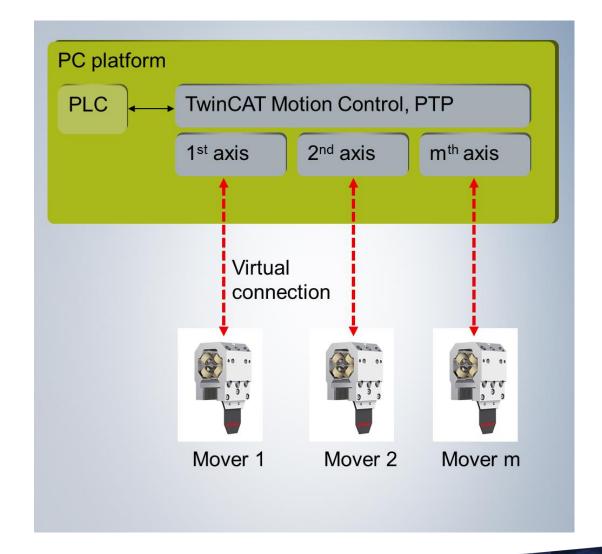
# The modular XTS system: the control system





# The control system: software and programming

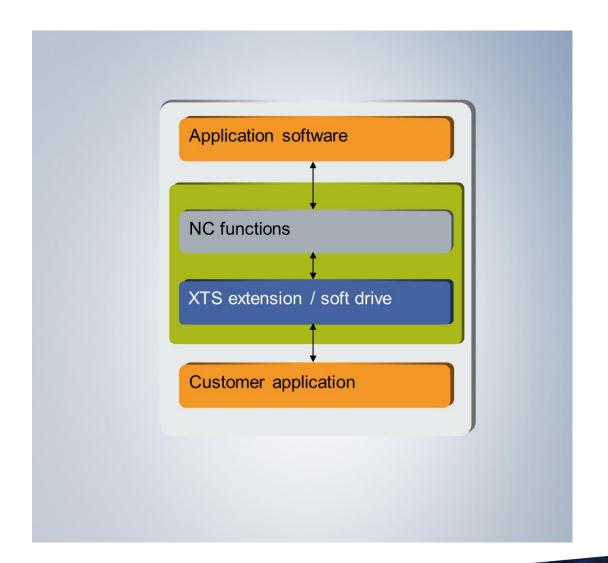
The XTS extension in TwinCAT 3 automation software decouples servo algorithms from the hardware components and calculates them centrally.



# The control system: software and programming

Regarding application programming, a mover appears like a "normal" servo axis.

- All motion control functions are available, for example:
  - flying saw
  - electrical gear unit
  - cam plates
- Functional extensions handle typical XTS requirements:
  - automatic accumulation
  - collision and jerk avoidance
  - centrifugal force limitation





## The control system: software and programming – XTS Configurator and XTS Viewer



 System configuration is automated to the greatest possible extent.



 Axis and control parameters of the movers can be copied.



- Intuitive online visualization of the moving movers in 2D.
- Diagnostic and simulation tool.

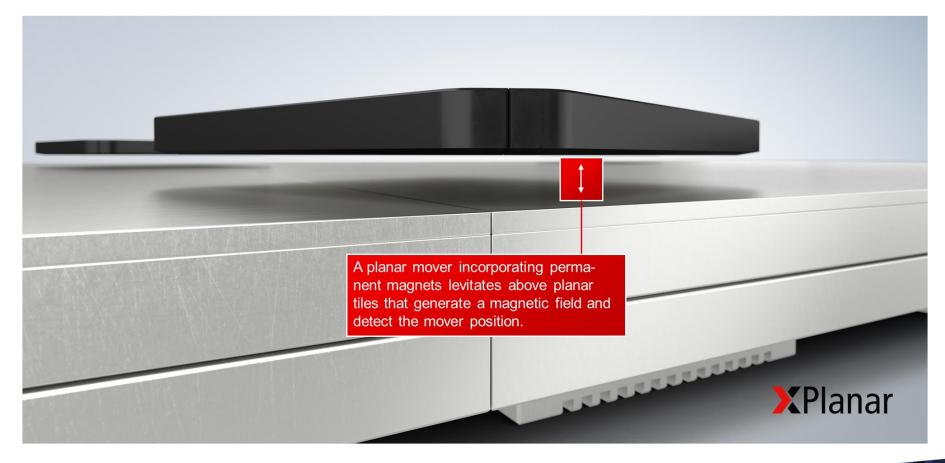


### XPlanar: Flying Motion



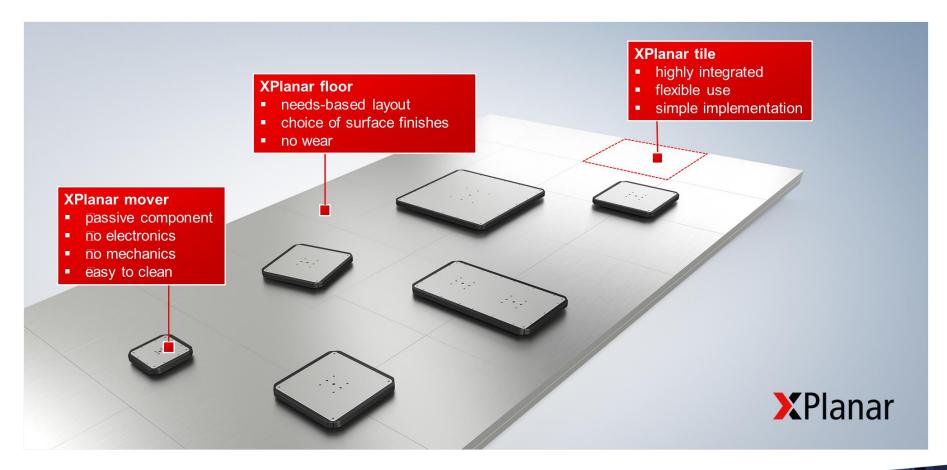


## XPlanar: free-floating movers for non-contact movement



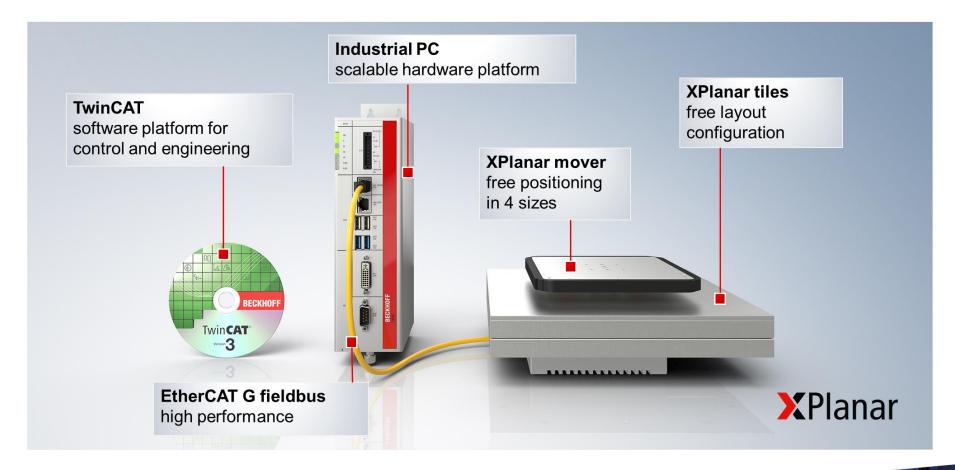


# XPlanar system: flying magnets with six degrees of freedom





## XPlanar system: minimum components, maximum design flexibility





## XPlanar movers: reaching every point in every way



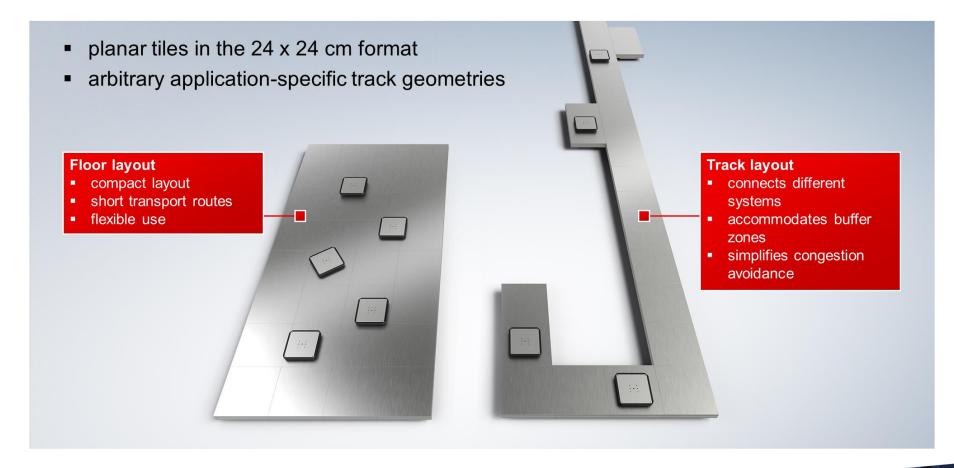


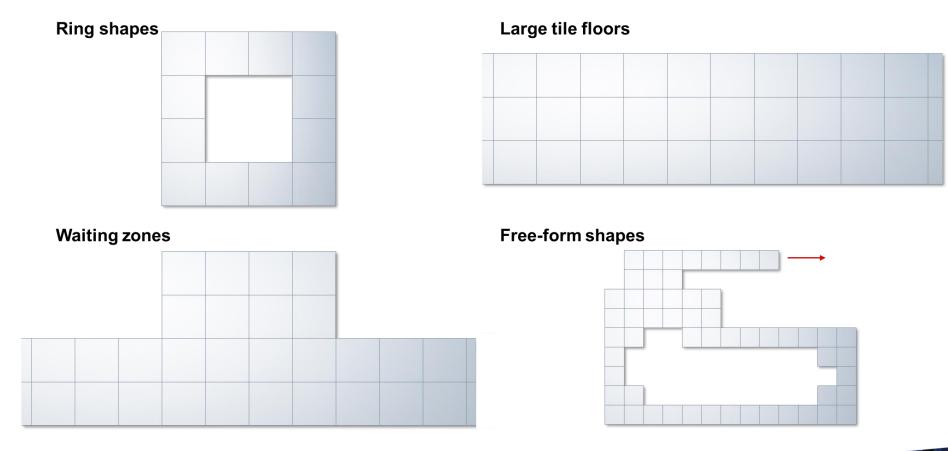
# XPlanar tile: planar motor with integrated position feedback

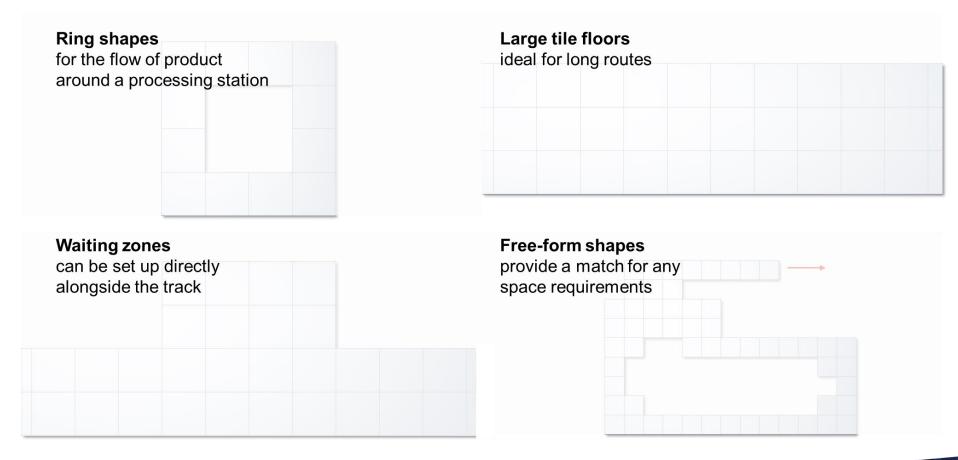
- The planar tile is highly integrated and unites all relevant functions.
- The mover positions are detected by the tiles.
- A power supply unit supplies the output stages with power.
- Super-flat coils generate the travelling magnetic field.
- EtherCAT G establishes a broadband connection to the Industrial PC.
- The tiles can be connected in series on a carrier construction on the machine side.



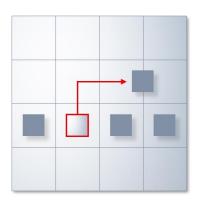




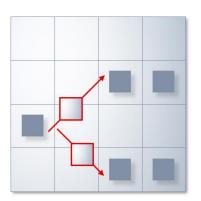




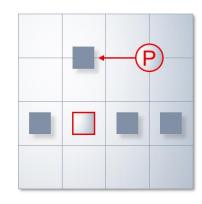
**Overtaking** 



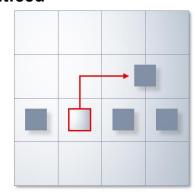
Divider



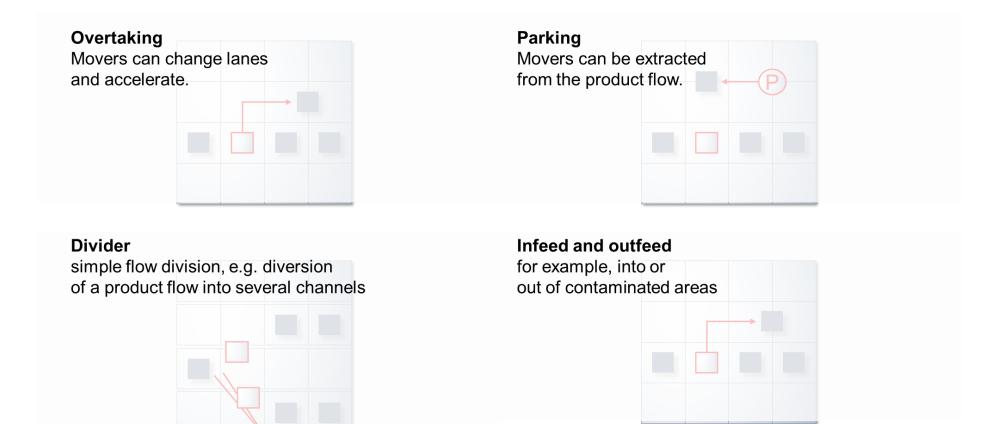
**Parking** 



Infeed and outfeed

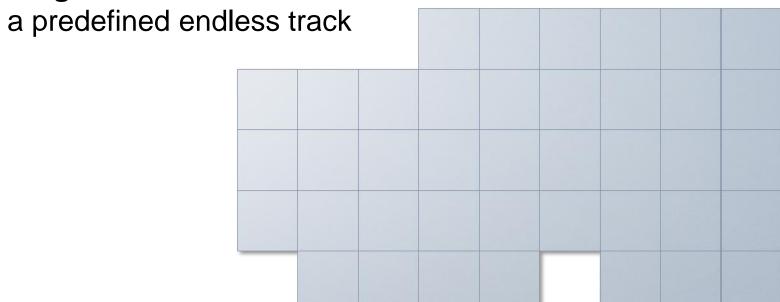






# XPlanar software: commissioning and track management

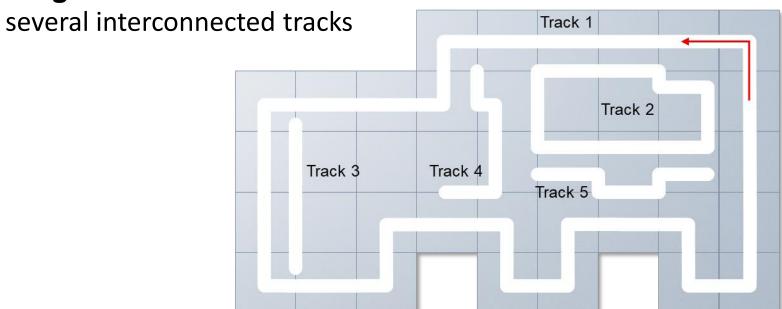
#### Stage 1





# XPlanar software: commissioning and track management

#### Stage 2

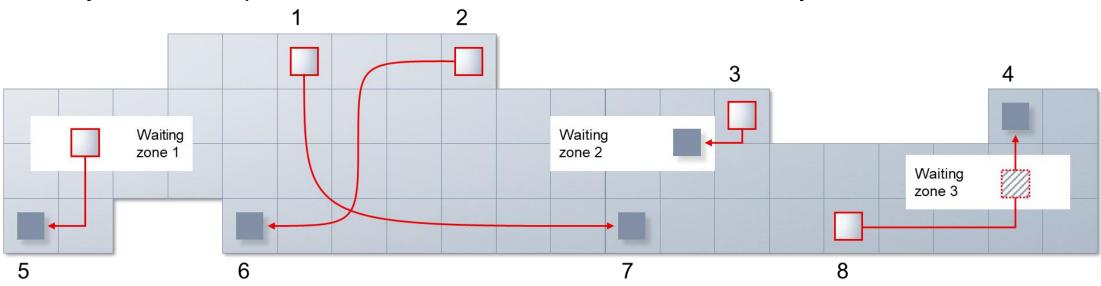




## XPlanar software: commissioning and track management

#### Stage 3

fully automatic path calculation: all movers can move freely.



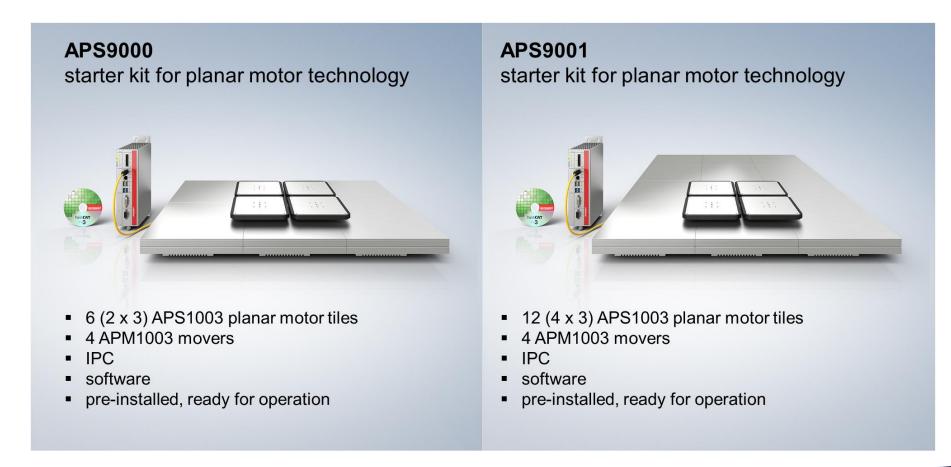


### XPlanar: product overview





### XPlanar starter kit: fully functional for a fast introduction



### XPlanar tiles

APS1003-0000 planar tile



- 4 active areas
- 110/230 V AC/24 V DC
- 240 mm x 240 mm x 67 mm (L x W x H)
- 4.0 kg

APS2003-0000 planar tile



- rotor area
- 110/230 V AC/24 V DC
- 240 mm x 240 mm x 67 mm (L x W x H)
- 4.0 kg



### XPlanar movers

### APM1002-0000 planar mover

### APM1003-0000 planar mover

- aluminum body, hard coated
- bottom side inox coated



- 95 x 95 x 12 mm,0.39 kg
- 0.4 kg payload



- 155 x 155 x 12 mm,
  1.27 kg
- 1.5 kg payload

### APM1005-0000 planar mover



- 155 x 275 x 12 mm,2.5 kg
- 3.0 kg payload

### APM1004-0000 planar mover



- 275 x 275 x 12 mm,5.0 kg
- 6.0 kg payload



### XPlanar: technical data

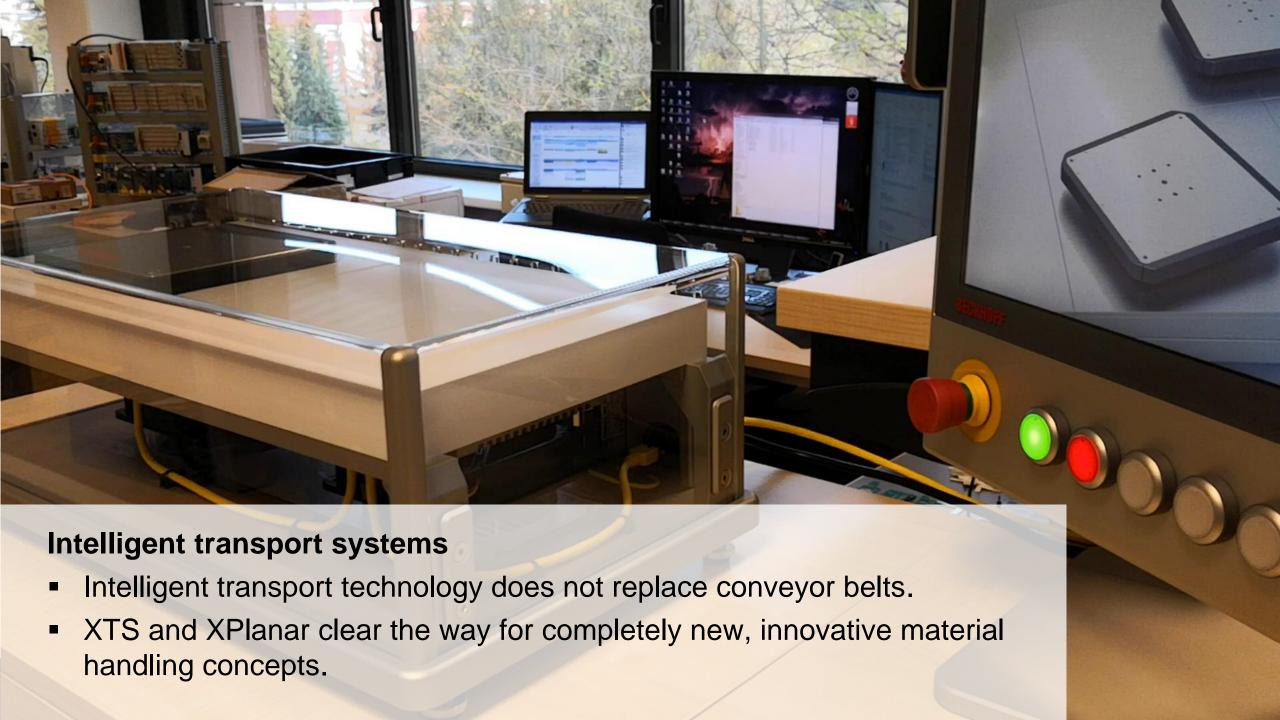
Mover	Technical data	Comment
Speed	4 m/s	
Acceleration	20 m/s²	without load
Max. load	6 kg	at low speed
Flight height without load	5 mm	
Flight height 1 kg load	1 mm	
Max. angle of rotation (±)	360°, ±15°	
Positioning accuracy		
Position resolution	1 μm (X, Y, Z), 0,001° (A, B, C)	
	0.001° (A, B, C)	
Absolute accuracy (±)	150 μm (X, Y, Z)	at 25° C, per module
	0.15° (A, B)	at 25° C
	0.2° (C)	at 25° C
Repeatability (±)	< 50 μm (X, Y, Z)	



### XPlanar: technical data

Power consumption	Technical data	Comment
In standby mode per planar module	13 W	
Per mover, 1 mm flight height, unloaded, at standstill	40 60 W	position dependent
Per mover, 1 mm flight height, unloaded, in motion	105 W	
Per mover, 2 mm flight height, unloaded, at standstill	50 75 W	position dependent
Per mover, 2 mm flight height, unloaded, in motion	115 W	







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