

Getting Ahead of the Game:

What changes when you deploy
robotic piece-picking

Presented by:

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Your Logo Goes Here!



MODEX 2020

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Key Takeaways

- If you've been on the fence with regard to using robots for piece-picking (item level handling), there are compelling solutions to consider
- The transition from all manual to a mix of robot and manual processing requires managing through a punch list of considerations before deploying robotic piece-picking within a warehouse
- Robotic picking systems are becoming more plug and play, so your system integrators should be able to work with you to address overall needs
- As robots become part of the team, it's important to think about how you will operationalize their use to maximum benefit



the accuracy and timeliness of the supply chain is critical for a company's brand



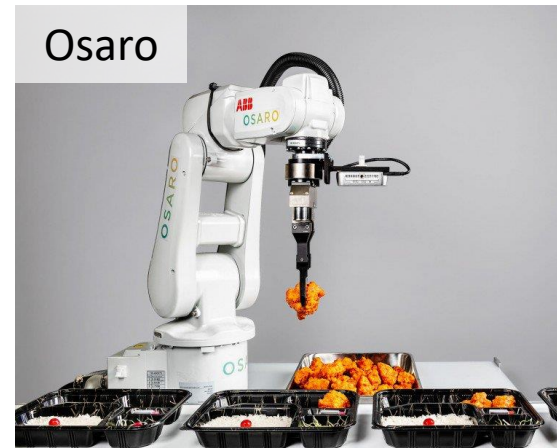
Pieces and people challenge

- Growth in online commerce means fewer lines and units per order
- Item handling is lower productivity than pallet or case picking
- Finding the required warehouse labor is already challenging
- Robotic automation provides an option to meet your customers' demand cost-effectively and reliably



A sampling of piece-picking bots

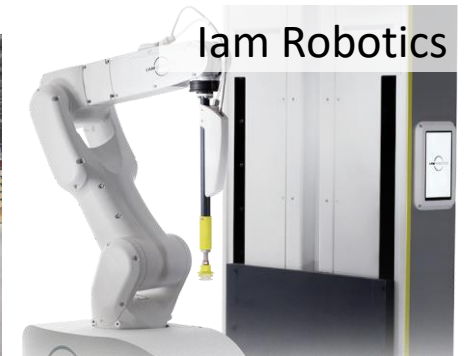
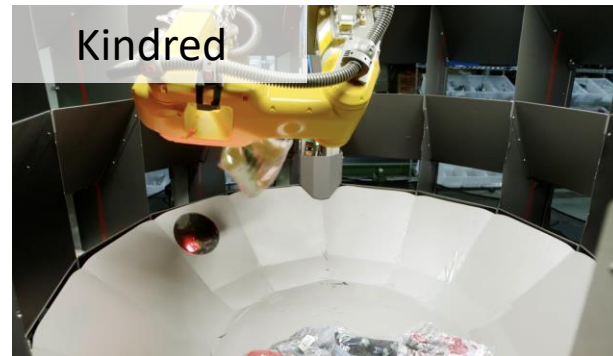
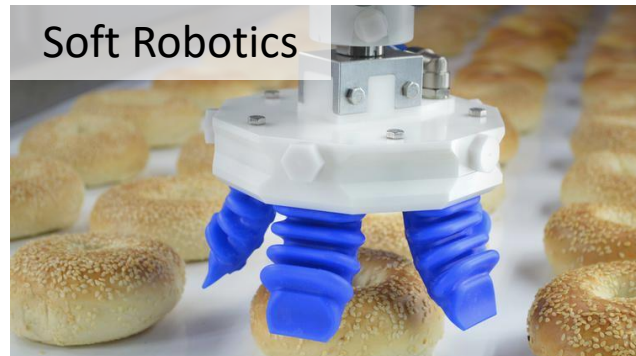
100s of millions
of picks by
EOY 2020



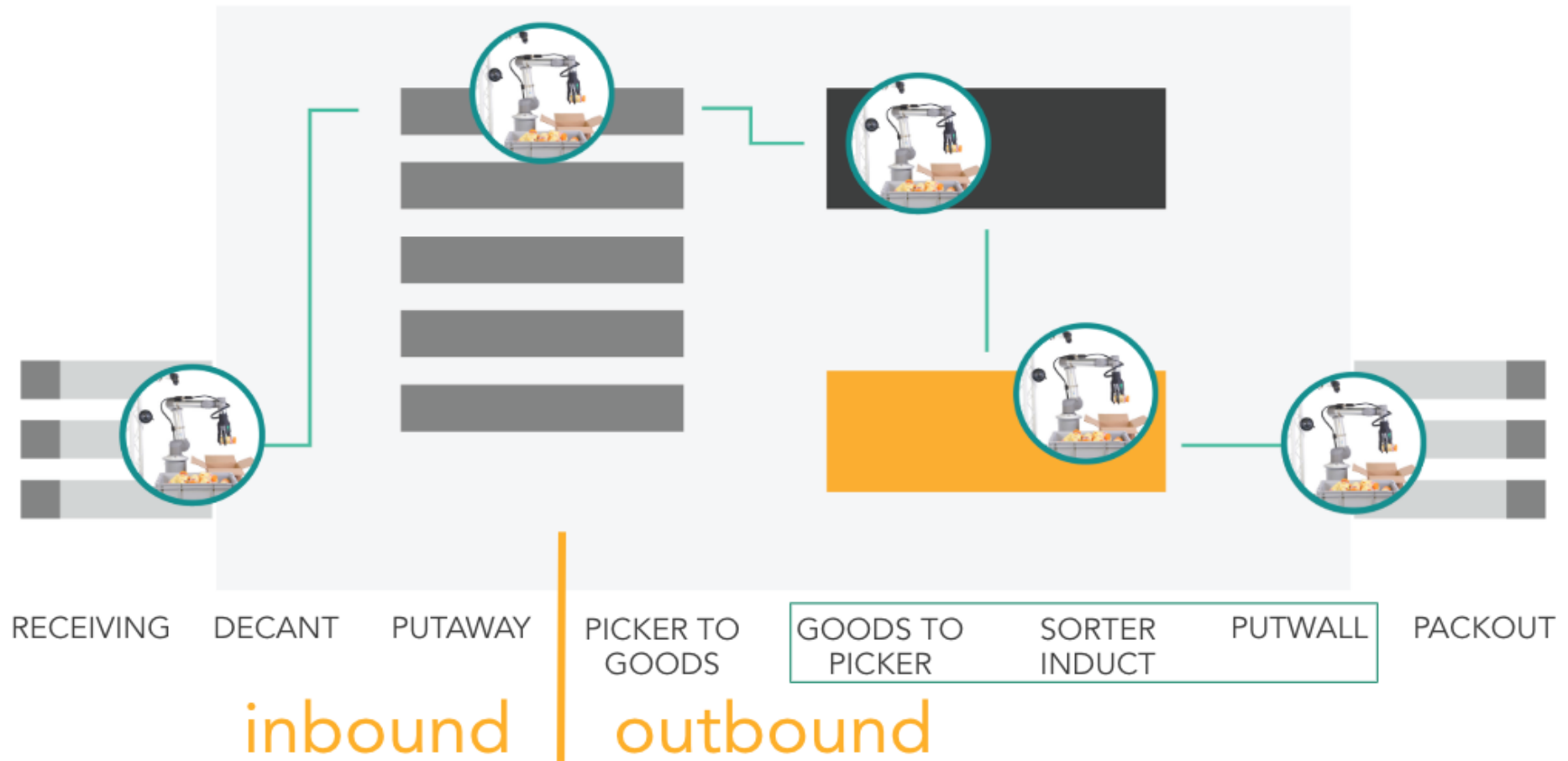
Still more piece-picking bots



- Range
- Rate
- Reliability

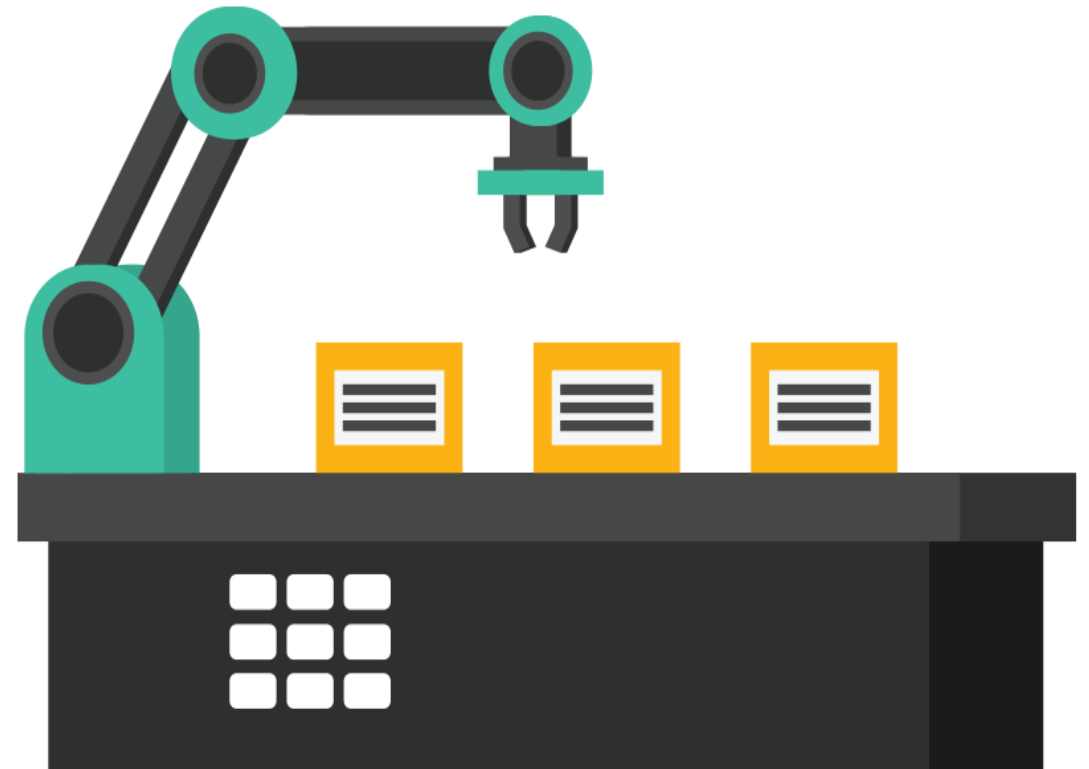


A vision for lights-out order fulfillment



Adopting robotic piece-picking systems

- With options to choose from, understand your picking needs:
 - strategic pillar or cost savings
 - range, rate, reliability (3Rs)
 - picking machine (Hand, Eye, Coordination) vs DIY
 - brownfield and / or greenfield designs
- Talk with your provider about
 - item set
 - operation model
 - workflow
 - physical workspace
 - software integration and routing



Item set

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Many items are pickable

Grocery



Health & Beauty



Pharma



Electronics & Consumer



Apparel



Some are not



Items that Tangle
(should be packaged)



Items with packaging that opens
(should fix packaging)



Porous, Complex Items
(tend to multi-pick)

Guidelines for Robot Pickable Items

| Parameter | Min | Max |
|-----------|------|-------|
| Weight | 0 kg | 2 kg |
| Length | 2 cm | 40 cm |
| Width | 2 cm | 20 cm |
| Height | 1 cm | 30 cm |



Bottles



Boxes



Bags



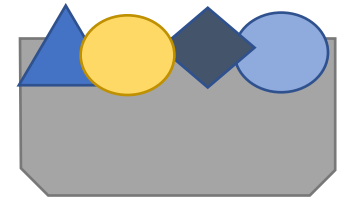
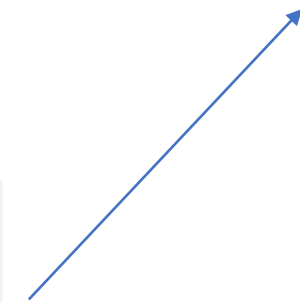
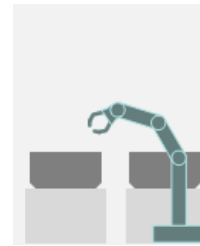
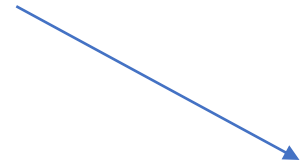
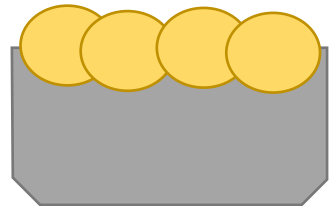
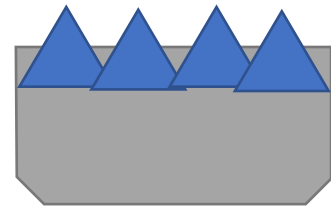
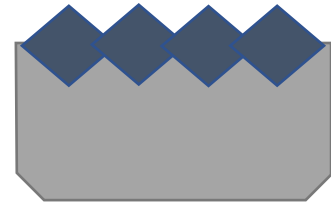
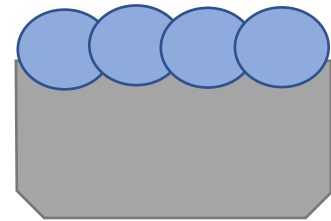
Blister Packs

Operation model

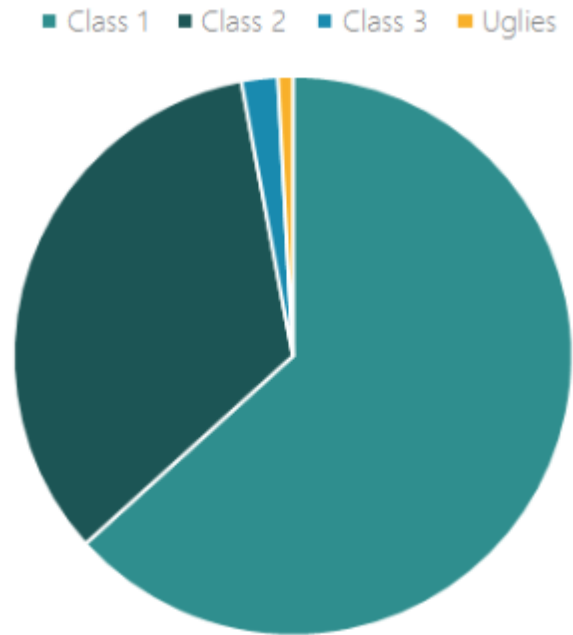
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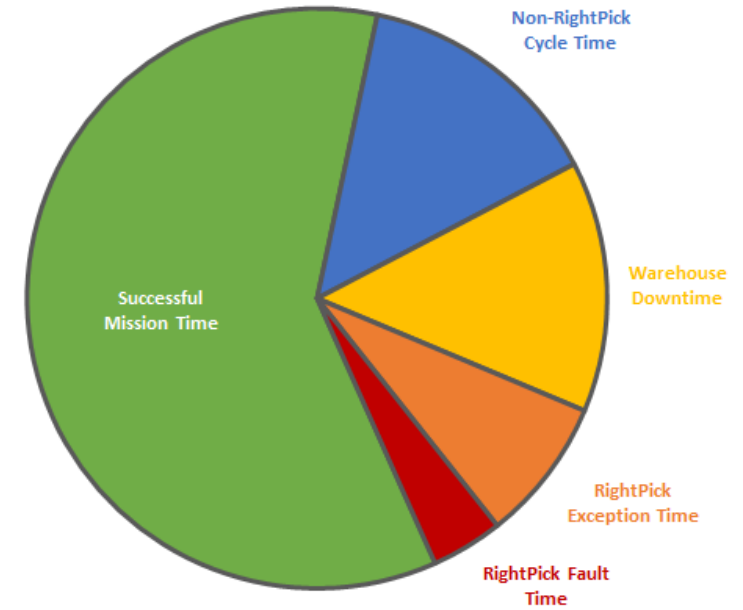
Handling pickable and “non-pickables”



Performance – a tale of two pie charts

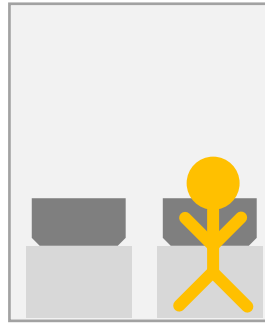
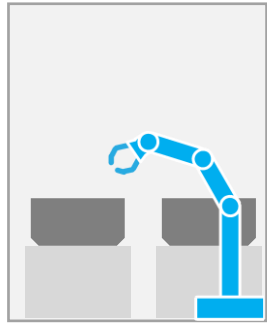


- Pickable Order Volume



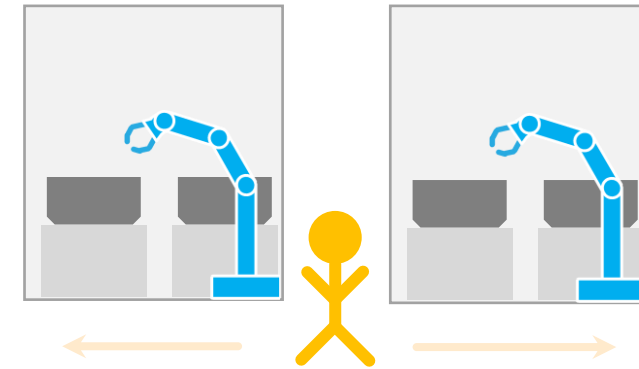
- Throughput (pieces/hr)

Handling unpickable and unclassified items



Robot Stations + Manual Stations

Robot items routed to robot
Manual items routed to person



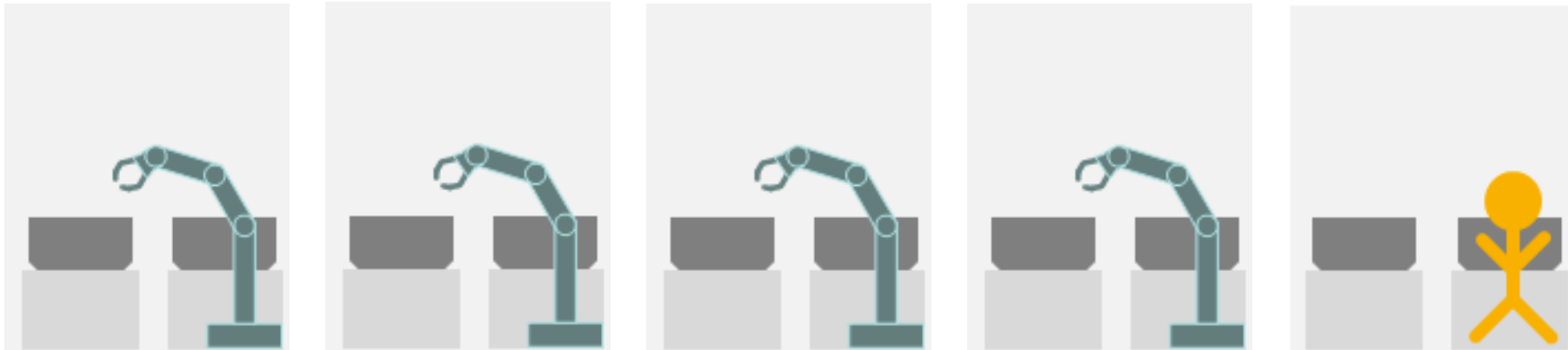
Robot Master

Most items picked by robot
Manual operator handles exceptions

Solution Design

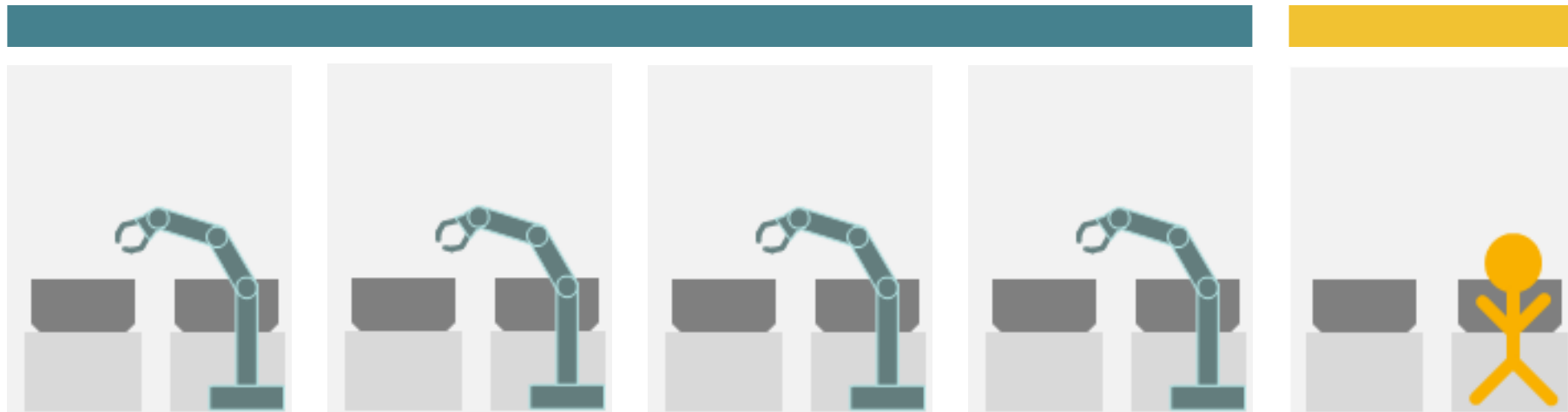
Promise: throughput, labor overhead, order integrity

Design: exception-handling (overseer, material flow, workstation features)



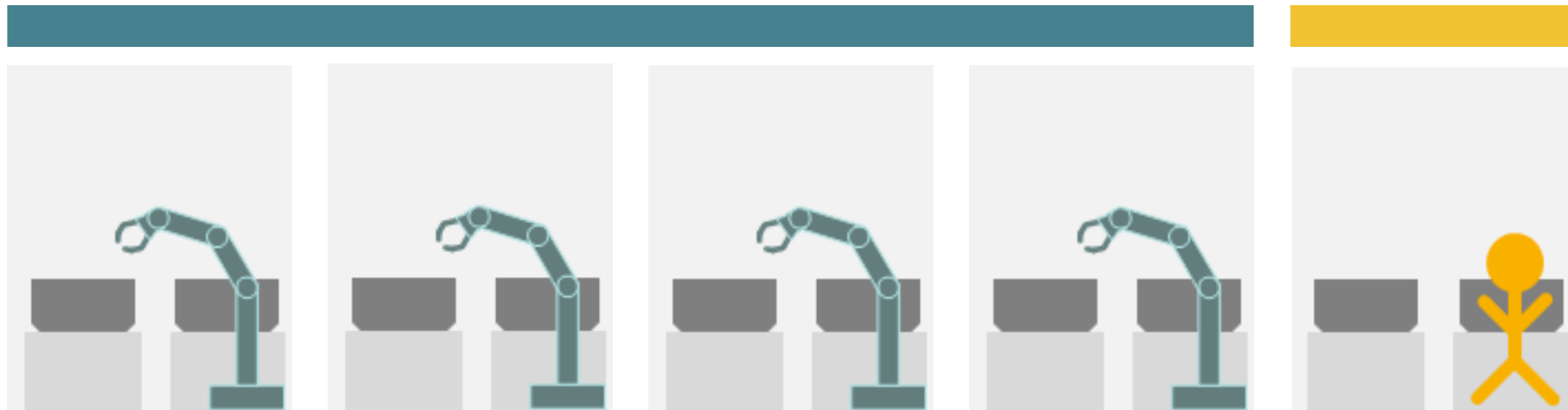
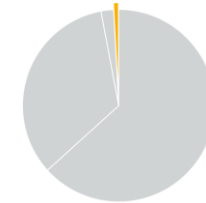
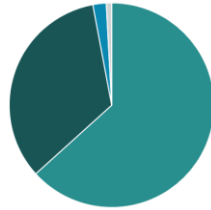
Solution Design

Number of stations



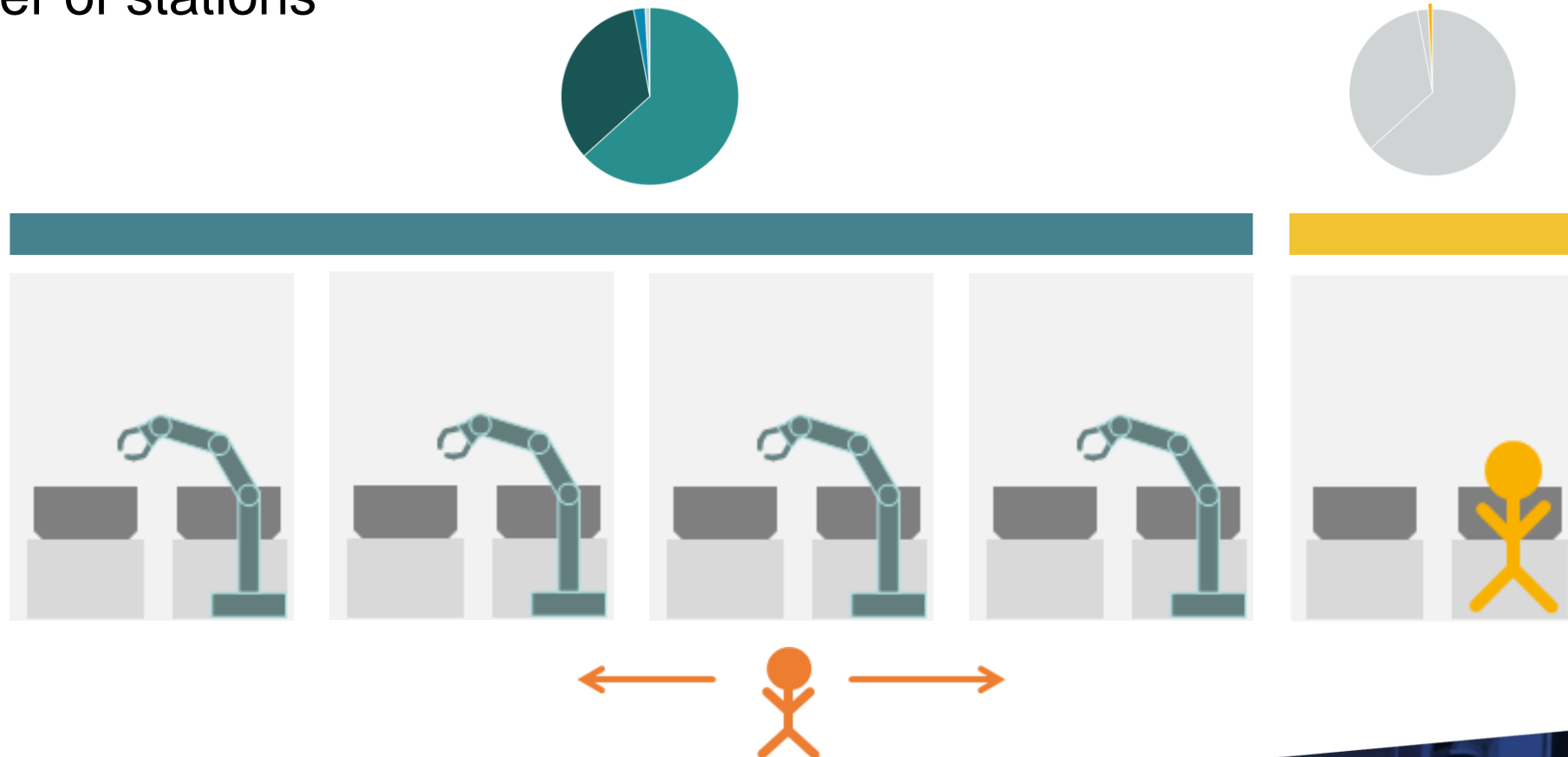
Solution Design

Number of stations



Solution Design

Number of stations



Workflow

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goods-to-picker



Physical workspace

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Robot-friendly workspace



1 source: 4 destinations



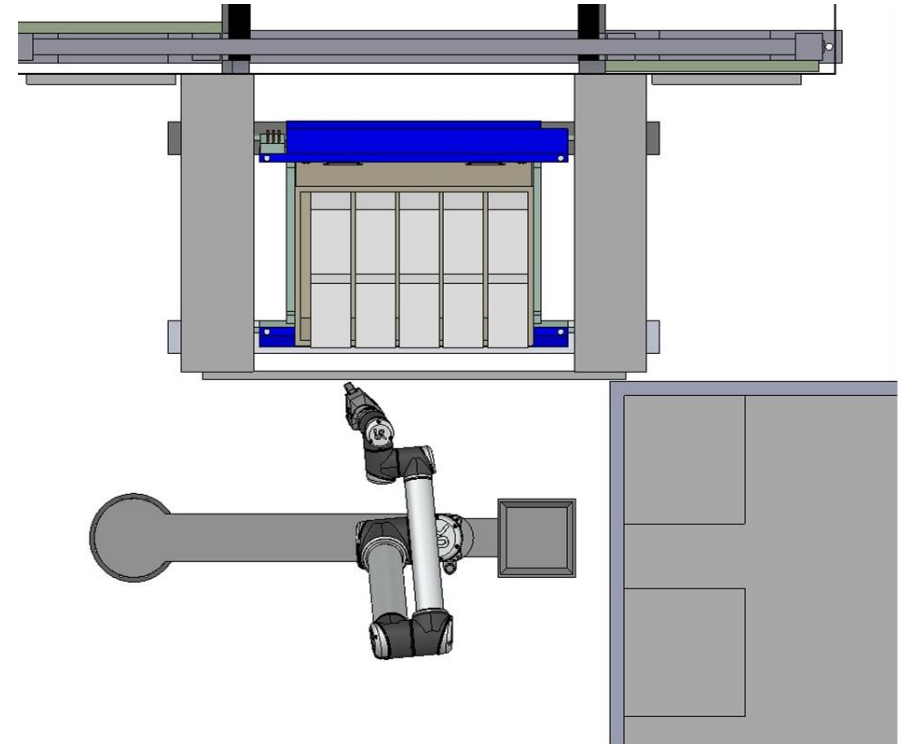
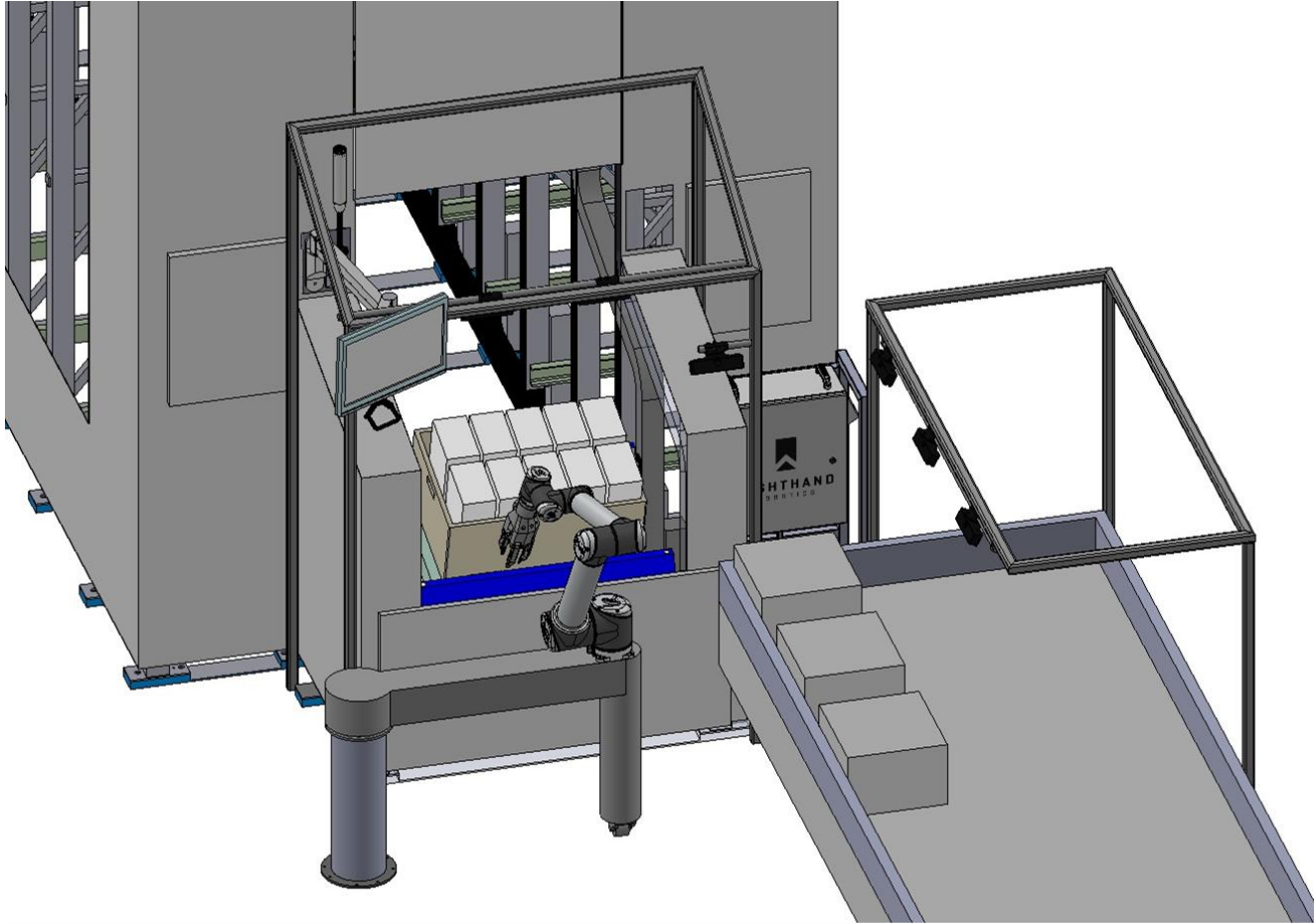
1 source: 1 destination

Within Robot Reach

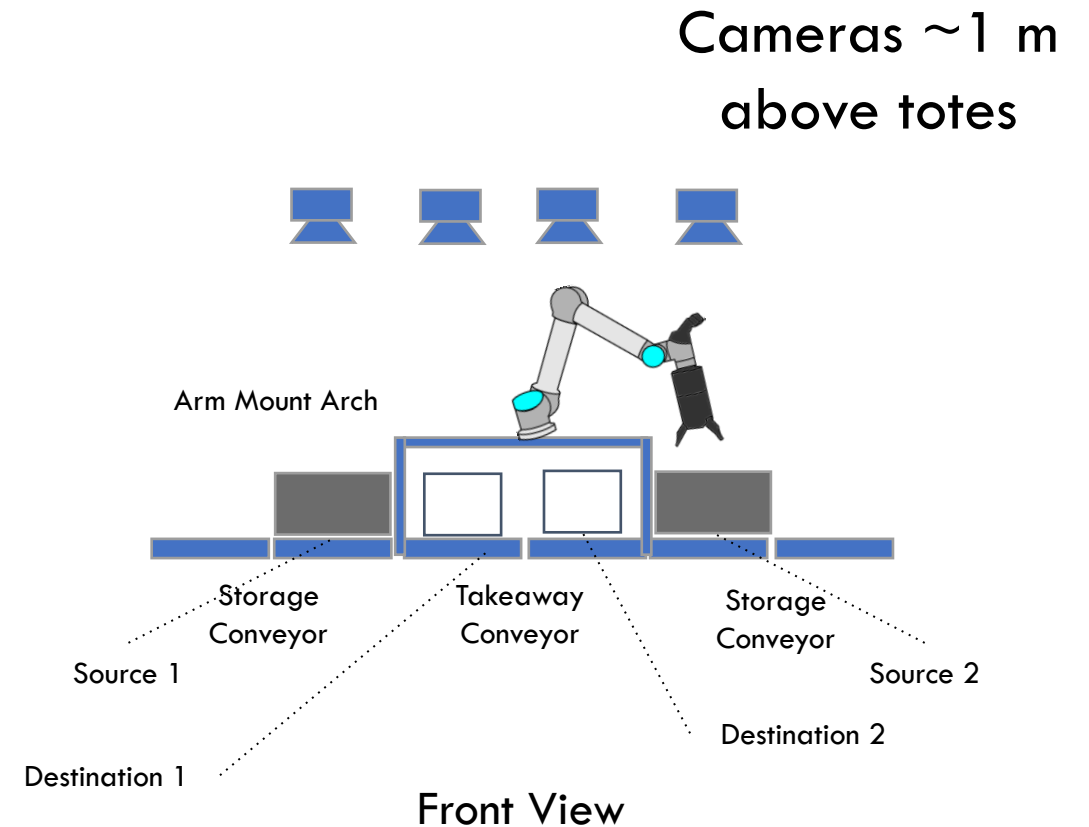
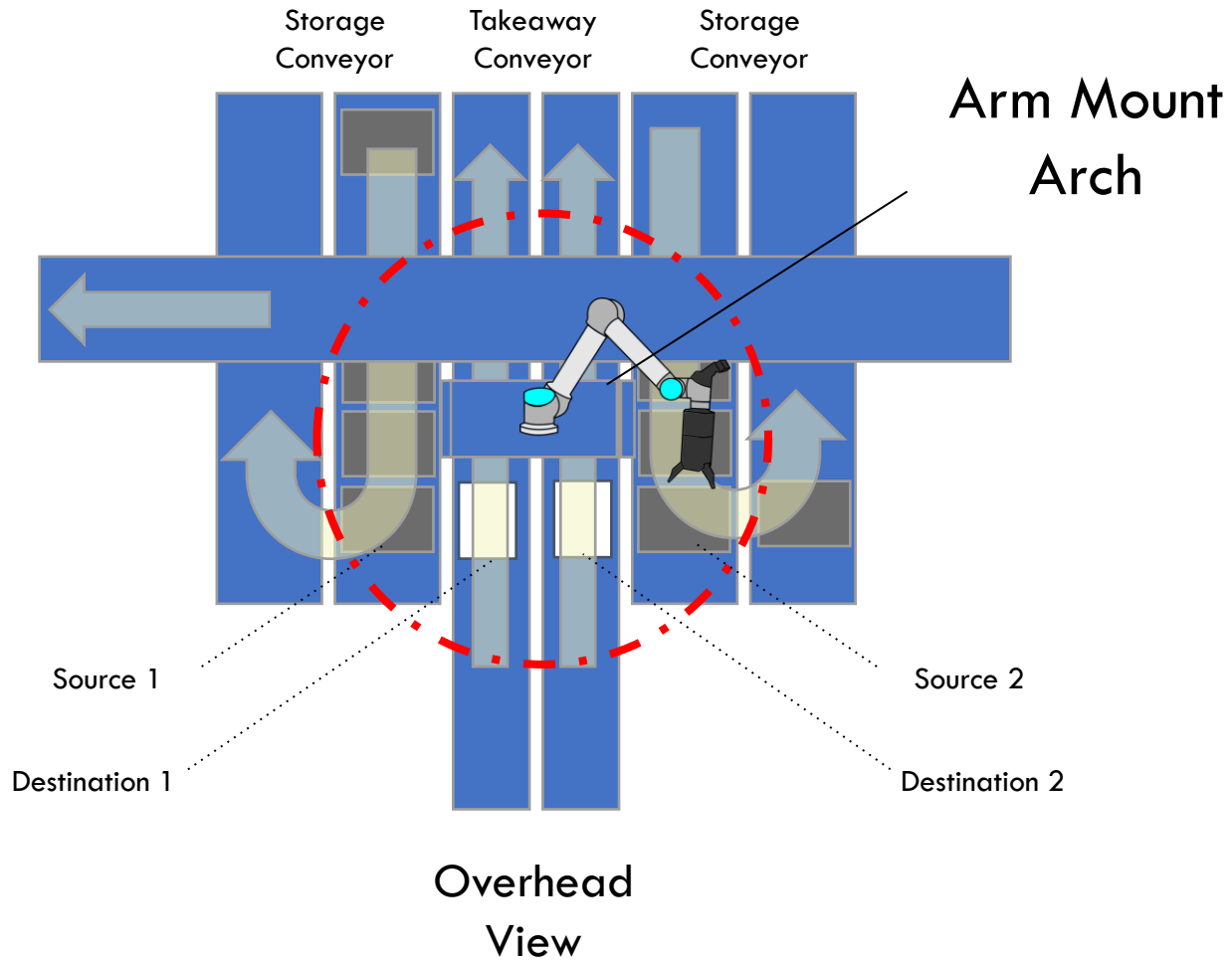


Open Order Container

Workstation design - overview



Example concept



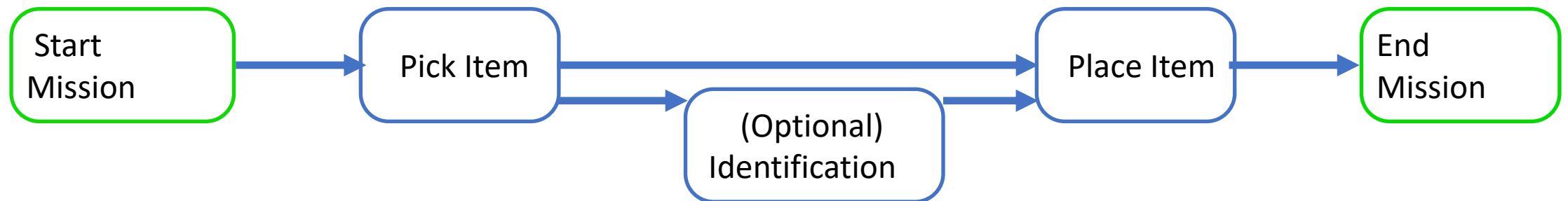
Software integration

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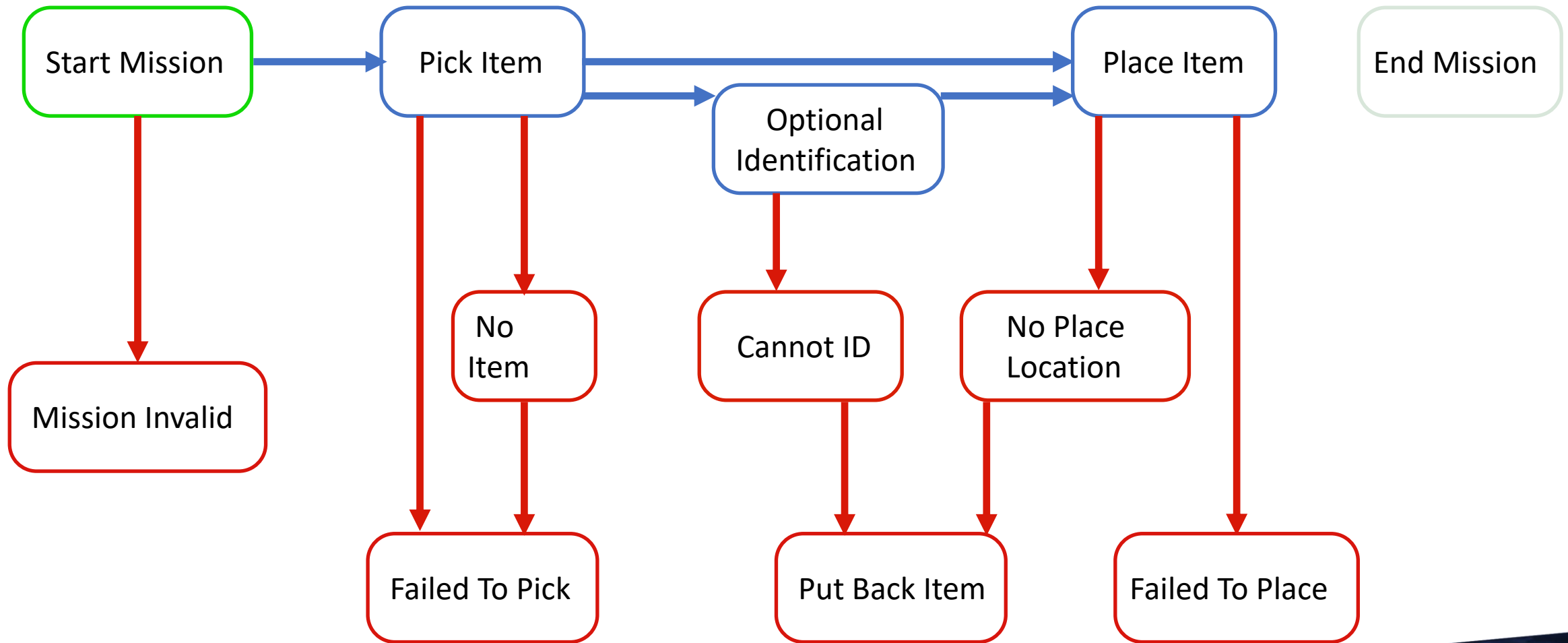


Software API – Mission Control Protocol

- Pick Mission is a set of instructions for a pick and place
- Each mission includes:
 - Pick information (source, destination, item, item metadata)
 - Place information (location, timing)
 - Result information sent from the robot
 - Status information sent back and forth every minute and as needed

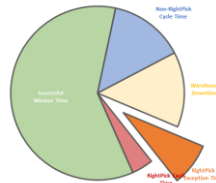
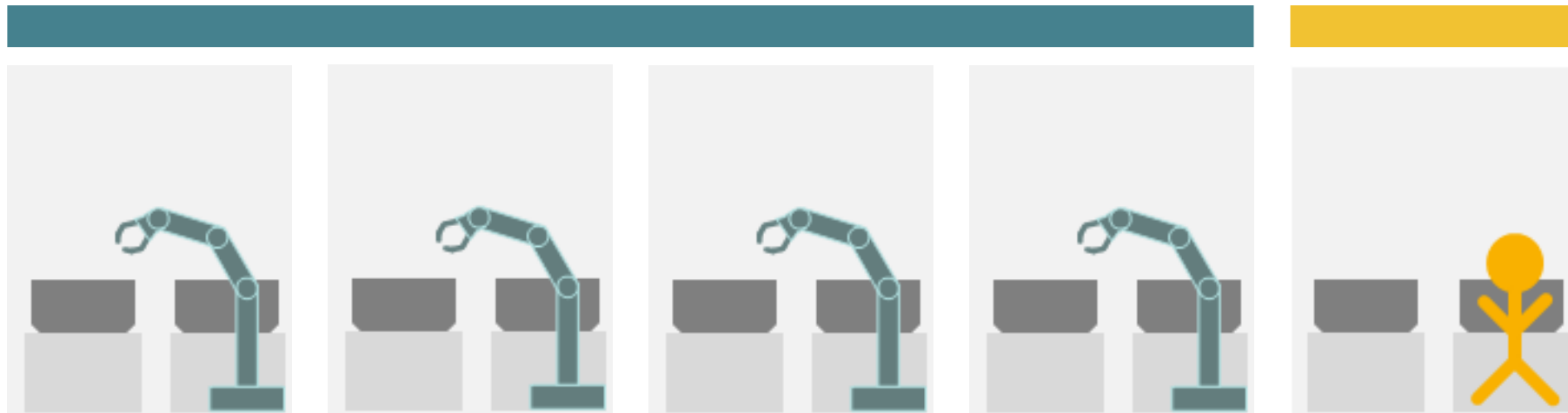
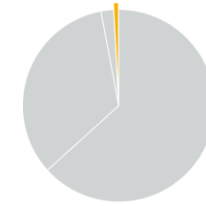
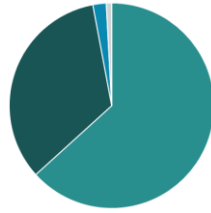


Mission Control Flow: Exceptions



Solution Design

Overseer labor, routing



Field example – multi-robot installation



Putting it all together

- At the pace with which the technology is maturing, now is the time to plan for robotic piece-picking
- Define business objectives, 3R needs, whether you want to make or buy and whether you benefit most from retrofits or greenfield projects
- Understand what's robot pickable and what really shouldn't be and work with your provider(s) to decide how you will manage some likely mix
- Select a workflow that is significant to your business and collaborate on workspace design, software integration and exception handling.
- Define a practical operational model and provide training for the team
- Track key metrics and iterate or adjust as needed – it may take some tuning to maximize the benefit



Thank you

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